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ENGINEERING RELIABILITY

FUNDAMENTALS OF PROBABILITY

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OUTLINE

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SUMMARY

- ▶ A **random variable** (denoted by X) is a variable that can assume one or more possible numerical values (denoted by x)
- ▶ The value x that X assumes is determined by chance
- ▶ A random variable may be:

- ▶ discrete

$$x \in \{1, 2, 3\}$$

- ▶ or continuous

$$x \in \{x | 0 \leq x < \infty\}$$



PROBABILITY DISTRIBUTION/PROBABILITY DENSITY

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SUMMARY

- ▶ for discrete random variables the **probability distribution function** is the set of probabilities

$$f(x) = P(X = x), \quad \text{and} \quad \sum_x f(x) = 1$$

- ▶ for continuous random variables the **(cumulative) probability function** is the function:

$$F(x) = P(X \leq x)$$

- ▶ for continuous random variables the probability distribution or **probability density** is:

$$f(x) = \frac{d}{dx}F(x), \quad \text{and} \quad \int_{-\infty}^{\infty} f(x) dx = 1$$



PROBABILITY OF FAILURE/RELIABILITY

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- ▶ Let the random variable T denote the time of failure of a product during service. Then the possible values of T are the set $0 < t < \infty$.
- ▶ The associated probability density is $f(t)$, the probability that failure occurs at time t is

$$F(t) = \int_0^t f(\tau) d\tau$$

- ▶ The **reliability function** is the probability of survival to time t

$$R(t) = P(T \geq t) = 1 - F(t) = \int_t^{\infty} f(\tau) d\tau$$



SAMPLE SPACE

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The underlying idea is that there is a well-defined trial and a set of possible outcomes.

EXAMPLE (FLIPPING A COIN 3 TIMES)

Flipping a coin 3 times yields the following set of outcomes:

$$\begin{aligned} \xi_1 &= TTT & \xi_2 &= TTH & \xi_3 &= THT & \xi_4 &= THH \\ \xi_5 &= HTT & \xi_6 &= HTH & \xi_7 &= HHT & \xi_8 &= HHH \end{aligned}$$

- ▶ **Sample space**, S , the set of all possible outcomes.
- ▶ **Elementary outcome**, ξ , the individual elements of S .



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Event A : a subset of the sample space. In general, an event is defined by a proposition about the elements in it.

EXAMPLE (FLIPPING A COIN 3 TIMES)

A is the event that a tail shows up on the second toss

$$A = \{\xi_1, \xi_2, \xi_5, \xi_6\}$$

Elementary event: $\{\xi\}$, where ξ is an elementary outcome.

Sure event: the entire sample space, S .

Impossible event: the empty set, \emptyset .

Complementary event: A^c consists of all events not in A .

Mutually Exclusive events: events that have pairwise empty intersections.



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SUMMARY

A probability measure is a function that assigns a 'likelihood' of occurrence to each subset of S (to each event)

A **Probability Measure** P is a function on the set of subsets of S that has the following properties:

- ▶ $P(S) = 1$
- ▶ $P(A) \geq 0$ for each $A \subset S$
- ▶ For any sequence of mutually exclusive events A_1, A_2, \dots

$$P(\cup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} P(A_i)$$



VENN DIAGRAMS

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The Venn diagram is an aid in visualizing basic properties of sets. It can also serve as a simple visual representation of the probability model.

- ▶ The sample space S is visualized as a rectangular set of points in the plane.
- ▶ The elementary outcomes are the points in S .
- ▶ The probability is associated with a the (non-uniform) distribution of a unit mass over the set S . In the case of a finite number of outcomes, the mass is concentrated at a finite number of points.



VENN DIAGRAMS

BASIC SET OPERATIONS

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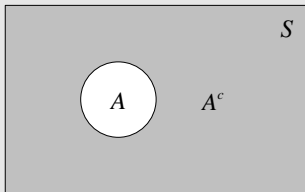
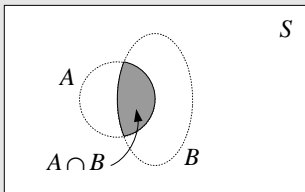
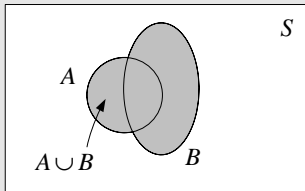
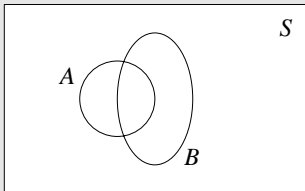
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CONDITIONAL PROBABILITY & INDEPENDENT EVENTS

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SUMMARY

The probability that an event A occurs, given the occurrence of an event B is called the **conditional probability of A given B** . It is denoted $P(A|B)$. From the Venn diagram we see that,

$$P(A \cap B) = P(A|B)P(B)$$

$$P(A|B) = \frac{P(A \cap B)}{P(B)}, \quad \text{if } P(B) \neq 0$$

Two events A and B are **independent** if the occurrence of one does not 'condition' the occurrence of the other, i.e.,

$$P(A|B) = P(A) \quad \text{and} \quad P(B|A) = P(B)$$

Thus, for independent events

$$P(A \cap B) = P(A)P(B)$$



INDEPENDENT EVENTS

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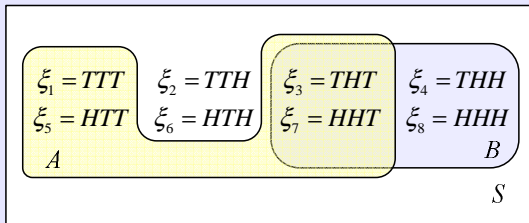
SUMMARY

EXAMPLE (FLIPPING A COIN 3 TIMES)

- ▶ reconsider the coin flipping experiment with sample space S shown below.
- ▶ let A be the event that a T occurs on the third toss.
- ▶ let B be the event that an H occurs on the second toss.

$$P(A) = \frac{1}{2}, \quad P(B) = \frac{1}{2}, \quad P(A|B) = \frac{1}{2}, \quad P(B|A) = \frac{1}{2}$$

Notice that the events are independent, but not mutually exclusive.





BAYES' RULE

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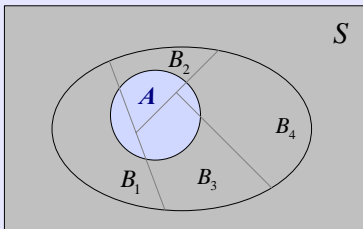
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SUMMARY



- expansion rule: $A \subset \cup_{i \in J} B_i$, events B_i mutually exclusive

$$P(A) = \sum_{i \in J} P(A|B_i) P(B_i)$$

- Bayes' rule: $A \subset \cup_{i \in J} B_i$, events B_i mutually exclusive

$$P(B_i|A) = \frac{P(B_i \cap A)}{P(A)} = \frac{P(A|B_i) P(B_i)}{\sum_{i \in J} P(A|B_i) P(B_i)}$$



ELEMENTARY COMBINATORICS

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SUMMARY

A *population of size n* is a set of n distinguishable elements.

Consider a population of size n from which we obtain an 'ordered' sample of size r .

- ▶ Sampling with replacement there are n^r possible samples.
- ▶ Sampling without replacement there are $(n)_r = n(n-1) \cdots (n-r+1)$ possible samples.
- ▶ Set $n = r$ to find that there are $n!$ different orderings of n elements.



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SUMMARY

We want to choose a subpopulation of size r from a population of size n . How many different such subpopulations are there?

- ▶ There are $(n)_r$ samples of size r without replacement,
- ▶ Each r -sample can be ordered in $r!$ ways,
- ▶ Thus, there are $(n)_r/r!$ subpopulations of size r .

$$\binom{n}{r} = \frac{(n)_r}{r!} = \frac{n(n-1)\cdots(n-r+1)}{r(r-1)\cdots 1} = \frac{n!}{r!(n-r)!} = C_r^n$$



BERNOULLI TRIALS

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SUMMARY

- ▶ By a **Bernoulli trial** we mean an experiment consisting of a sequence of independent trials with two possible outcomes, *success* and *failure*, having probability of failure p and probability of success $q = 1 - p$.
- ▶ *Fundamental Problem*: Consider a Bernoulli trial of Length n . What is the probability of exactly k failures?
- ▶ The event ' n trials results in k failures and $n - k$ successes' can happen in as many ways as k letters F can be distributed among n places.
- ▶ In other words, i.e., how many subpopulations of size k can be constructed from a population of size n ? The event consists of:

C_k^n points, each with probability $p^k q^{n-k}$



BINOMIAL DISTRIBUTION

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SUMMARY

The probability that n Bernoulli trials with probability p for failure and $q = 1 - p$ for success results in k failures and $n - k$ successes is given by the *Binomial distribution*:

$$b(k; n, p) = \binom{n}{k} p^k q^{n-k}, \quad 0 \leq k \leq n$$



POISSON APPROXIMATION

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SUMMARY

If

- ▶ the probability of failure p is small,
- ▶ the number of trials n is large, so that $np = \lambda$, a constant

then a good approximation to the Binomial distribution is the *Poisson distribution*:

$$p(k; \lambda) = e^{-\lambda} \frac{\lambda^k}{k!}, \quad \lambda = np$$



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SUMMARY

A function $X(\cdot)$ that maps a sample space S to the real numbers R is called a (real valued) random variable if it has the property:

$$\{\xi \in S | X(\xi) \leq x\} \text{ is an event } \forall x \in R$$

All elementary outcomes that result in $X(\xi) \leq x$ is a valid subset of S , for all real x .

- ▶ A random variable is discrete if it can assume a finite set of distinct values, say $x_i, i = 1, \dots, n < \infty$
- ▶ A random variable is continuous if the values it can assume are continuously distributed over its range, say $-\infty < x < \infty$



DISCRETE RANDOM VARIABLES

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SUMMARY

- ▶ $f(x_i) = P(X = x_i)$ is called the **probability distribution**,
note: $\sum_i f(x_i) = 1$
- ▶ the **(cumulative) probability function** is:
 $F(x_k) = \sum_{i=1}^k f(x_i)$
note: $F(x_k) = P(X \leq x_k)$
- ▶ mean: $\mu = \sum_{i=1}^n x_i f(x_i)$
- ▶ variance: $\sigma^2 = \sum_{i=1}^n (x_i - \mu)^2 f(x_i)$
- ▶ standard deviation: σ



COIN FLIPPING EXAMPLE

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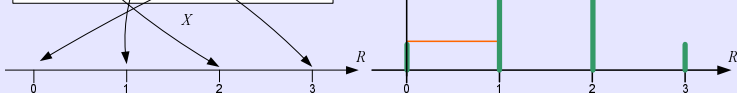
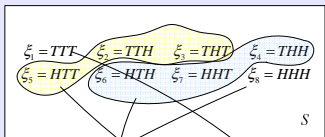
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EXAMPLE (FLIPPING A COIN 3 TIMES)

- ▶ Flipping a coin 3 times yields a set of 8 outcomes.
- ▶ Assume: on a single toss, $P(H) = P(T) = 1/2$.
- ▶ Define: X = number of tails in 3 tosses.





CONTINUOUS RANDOM VARIABLES

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SUMMARY

- ▶ the (cumulative) probability function is:

$$F(x) = P(X \leq x)$$

- ▶ the probability distribution (density) is:

$$f(x) = \frac{d}{dx}F(x) \Rightarrow \int_{-\infty}^{\infty} f(x)dx = 1$$

- ▶ mean: $\mu = \int_{-\infty}^{\infty} xf(x)dx$

- ▶ variance: $\sigma^2 = \int_{-\infty}^{\infty} (x - \mu)^2 f(x)dx$

- ▶ standard deviation: σ



CONTINUOUS RANDOM VARIABLES, CONT'D

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- ▶ median: $x_m, F(x_m) = \int_{-\infty}^{x_m} f(x) dx = \frac{1}{2}$
- ▶ mode: $x_{\text{mode}}, f(x_{\text{mode}}) \geq f(x)$
- ▶ skewness: $sk = \frac{1}{\sigma^3} \int_{-\infty}^{\infty} (x - \mu)^3 f(x) dx$

Comments on skewness:

- ▶ $sk > 0 \Rightarrow$ left – skewed : $x_{\text{mode}} < x_m < \mu$
- ▶ $sk < 0 \Rightarrow$ right – skewed : $x_{\text{mode}} > x_m > \mu$
- ▶ $sk = 0 \Rightarrow$ symmetric : $x_{\text{mode}} = x_m = \mu$



EXAMPLE – POISSON DISTRIBUTION

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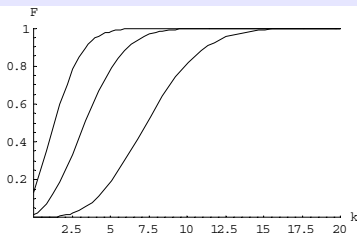
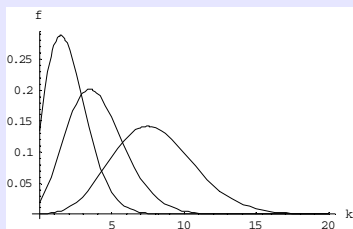
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SUMMARY

$$f(k) = e^{-\lambda} \frac{\lambda^k}{k!}$$

$$F(k) = \sum_{i=1}^k e^{-\lambda} \frac{\lambda^i}{i!} = \frac{(1+k) \Gamma(1+k, \lambda)}{\Gamma(2+k)}$$

Here is the Poisson distribution for $\lambda = 2, 4, 8$ (left to right)





EXAMPLE – POISSON DISTRIBUTION, CONT'D

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$$\mu = \sum_{k=0}^{\infty} k \left(e^{-\lambda} \frac{\lambda^k}{k!} \right) = \lambda$$

$$\sigma^2 = \sum_{k=0}^{\infty} (k - \mu)^2 \left(e^{-\lambda} \frac{\lambda^k}{k!} \right) = \lambda$$

$$sk = \frac{1}{\sigma^3} \sum_{k=0}^{\infty} (k - \mu)^3 \left(e^{-\lambda} \frac{\lambda^k}{k!} \right) = \frac{1}{\sqrt{\lambda}}$$



THE NORMAL DISTRIBUTION

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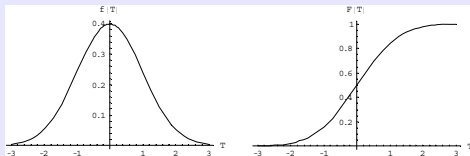
SUMMARY

The **normal distribution** has two key applications in reliability:

- ▶ It is a good model for the variability of parameters in batch-manufactured parts.
- ▶ It is a good approximation to the 'wear-out' time to failure distribution.

$$f(T) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2}\left(\frac{T-\mu}{\sigma}\right)^2}$$

where μ is the mean time to failure and σ is the standard deviation of the time to failure.





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The normal distribution is commonly used that the **standard normal distribution** has been introduced to facilitate computations. Suppose X is a normally distributed random variable with mean μ and standard deviation σ . Consider a new random variable Z , related to X , by the relation

$$Z = (X - \mu)/\sigma$$

Clearly,

$$P(X \leq x) = P(Z \leq (x - \mu)/\sigma)$$

Equivalently,

$$F(x) = \Phi((x - \mu)/\sigma)$$

where $F(x)$ is the probability function for X and $\Phi(z)$ is that of Z . Thus,

$$f(x) = \frac{dF(x)}{dx} = \frac{d\Phi(z)}{dz} \frac{dz}{dx} = \phi(z) \frac{dz}{dx}$$



STANDARD NORMAL DISTRIBUTION – 2

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It follows that

$$\phi(z) = \left[f(x) \left(\frac{dz}{dx} \right)^{-1} \right]_{x \rightarrow \sigma z + \mu} = \left[\frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2} \left(\frac{x-\mu}{\sigma} \right)^2} \sigma \right]_{x \rightarrow \sigma z + \mu}$$

So,

$$\phi(z) = \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}z^2}$$

and

$$\Phi(z) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^z e^{-\frac{1}{2}\zeta^2} d\zeta$$

The standard normal is the normal distribution with zero mean and unit variance. Its usefulness follows from the fact that

$$F(x) = \Phi((x - \mu)/\sigma), \quad f(x) = \phi((x - \mu)/\sigma)$$



DETERMINING DISTRIBUTION PARAMETERS FROM DATA

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EXAMPLE (FLAT PANEL MONITOR)

A flat pane computer monitor is designed to operate for 10,000 hours. Data shows that 2% fail within 1000 hours and 3.8% fail before 2000 hours. Assuming a normal time to failure distribution, determine the mean time to failure.

$$F(t) = \int_{-\infty}^t f(\tau) d\tau = \frac{1}{2} \left(1 + \operatorname{Erf} \left[\frac{t - \mu}{\sqrt{2} \sigma} \right] \right)$$

We can obtain the unknown parameters μ, σ from the two relations

$$F(1000) = 0.02, F(2000) = 0.038 \Rightarrow \mu = 8351, \sigma = 3580$$



BAYES' RULE – CONTINUOUS RANDOM VARIABLES

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SUMMARY

Suppose X and Y are random variables. The following quantities are defined:

- ▶ **joint probability distribution** is

$$F(x, y) = P(X \leq x) \cap P(Y \leq y)$$

- ▶ **joint probability density function** is

$$f(x, y) = \frac{\partial^2}{\partial x \partial y} F(x, y)$$

- ▶ **conditional density function for X given Y**

$$f(x|y) = \frac{f(x, y)}{f(y)}$$

Bayes rule for densities

$$f(x|y) = \frac{f(y|x)f(x)}{\int_{-\infty}^{\infty} f(y|x)f(x) dx}$$



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SUMMARY

- ▶ Random variable, probability, reliability
- ▶ Sample space, events
- ▶ Conditional probability, Bayes' rule
- ▶ Combinatorics, Bernoulli trials
- ▶ Discrete random variables - Binomial and Poisson distributions
- ▶ Continuous random variables - Normal distribution
- ▶ Mean, variance skewness, median, mode